



# Status of test beam simulation in Mokka



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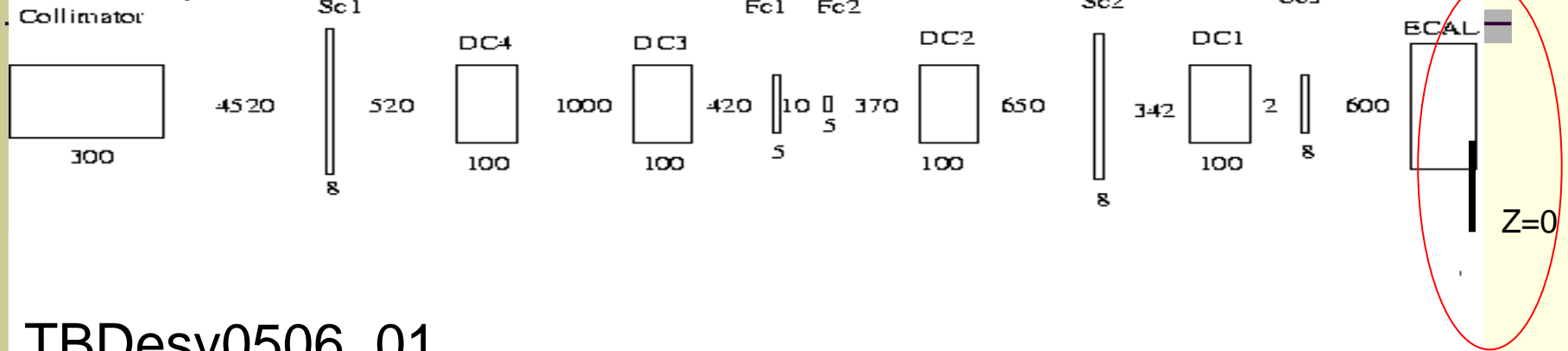
# Simulation of 2006 test beams

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- Setup of **2006 test beams** at **Desy** and **CERN** has been simulated in detail in Mokka
  - Latest version of **Mokka is 06-03p02**
- **Different test beam models** have been implemented
  - **'Old' coordinate system:** origin of coordinate system on the **back plane of the ECAL**
    - **Desy tb:** model **TBDesy0506**
    - **CERN Aug tb:** model **TBCern0806**
    - **CERN Oct tb:** model **TBCern1006**
  - **'New' coordinate system:** origin of coordinate system on the **back plane of DC closer to ECAL (DC1)**
    - **Desy tb:** model **TBDesy0506\_01**
    - **CERN Aug tb:** model **TBCern0806\_01**
    - **CERN Oct tb:** model **TBCern1006\_01**

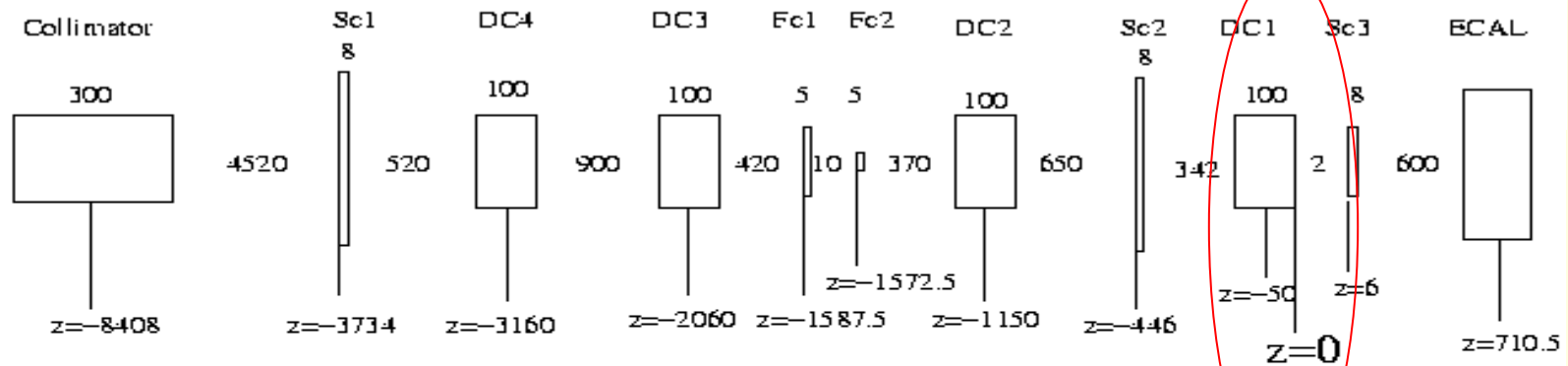
# Sketch of Desy models

## TBDesy0506

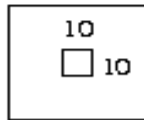


## TBDesy0506\_01

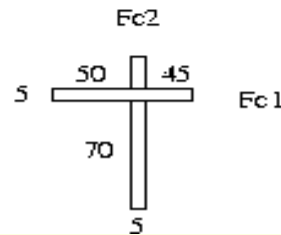
### TOP – Desy May 2006



FRONT



Sc1 and Sc2 are 200x200  
Sc3 is 120x120

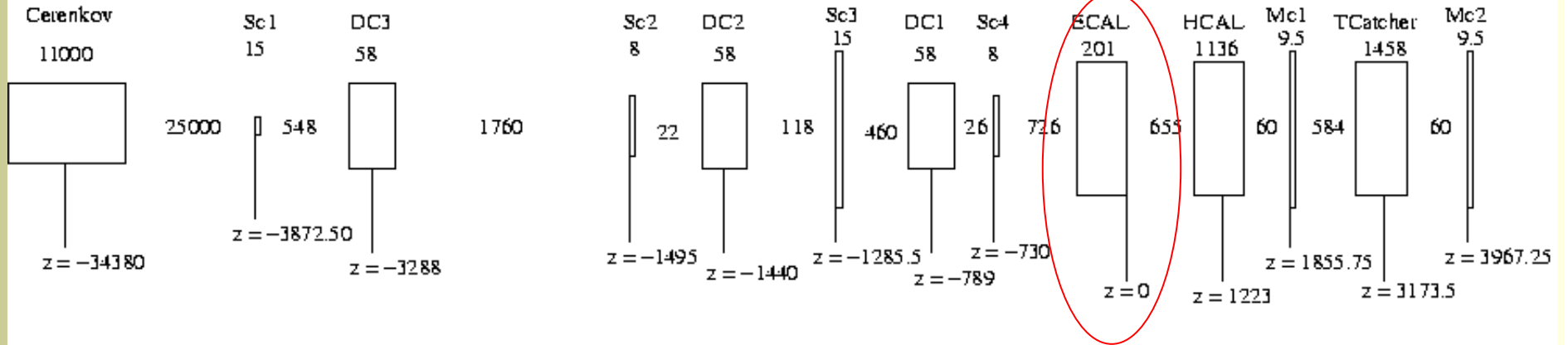


All distances are in mm

# Sketch of CERN Aug models

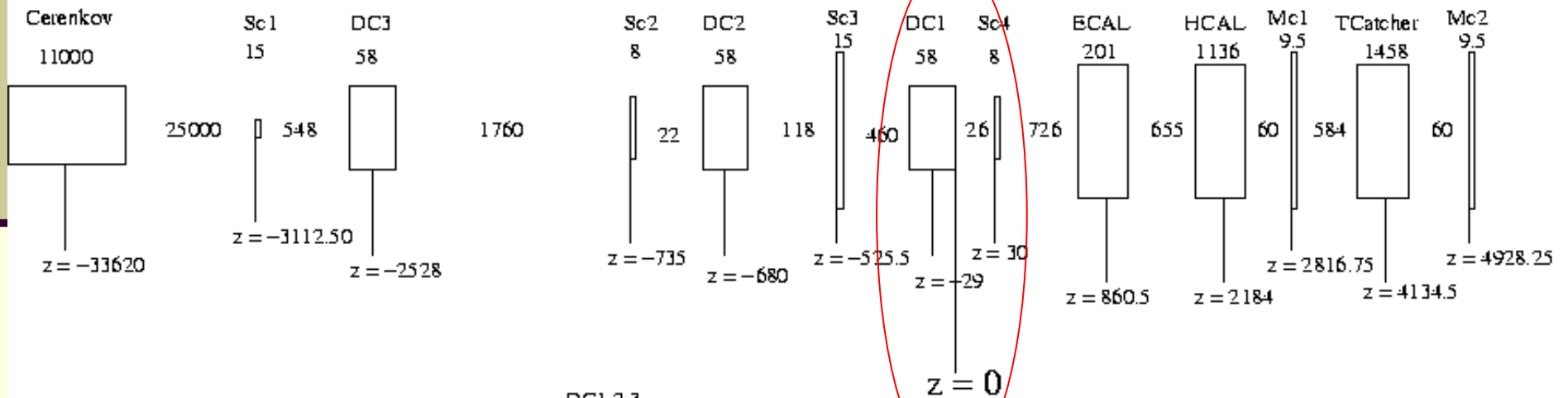
## TBCern0806

TOP



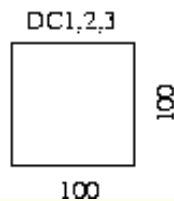
## TBCern0806\_01

TOP – CERN August 2006



FRONT

Sc1 is 30x30  
 Sc2 and Sc4 are 100x100  
 Sc3 is 200x200



Mc1 and Mc2 are 1000x1000

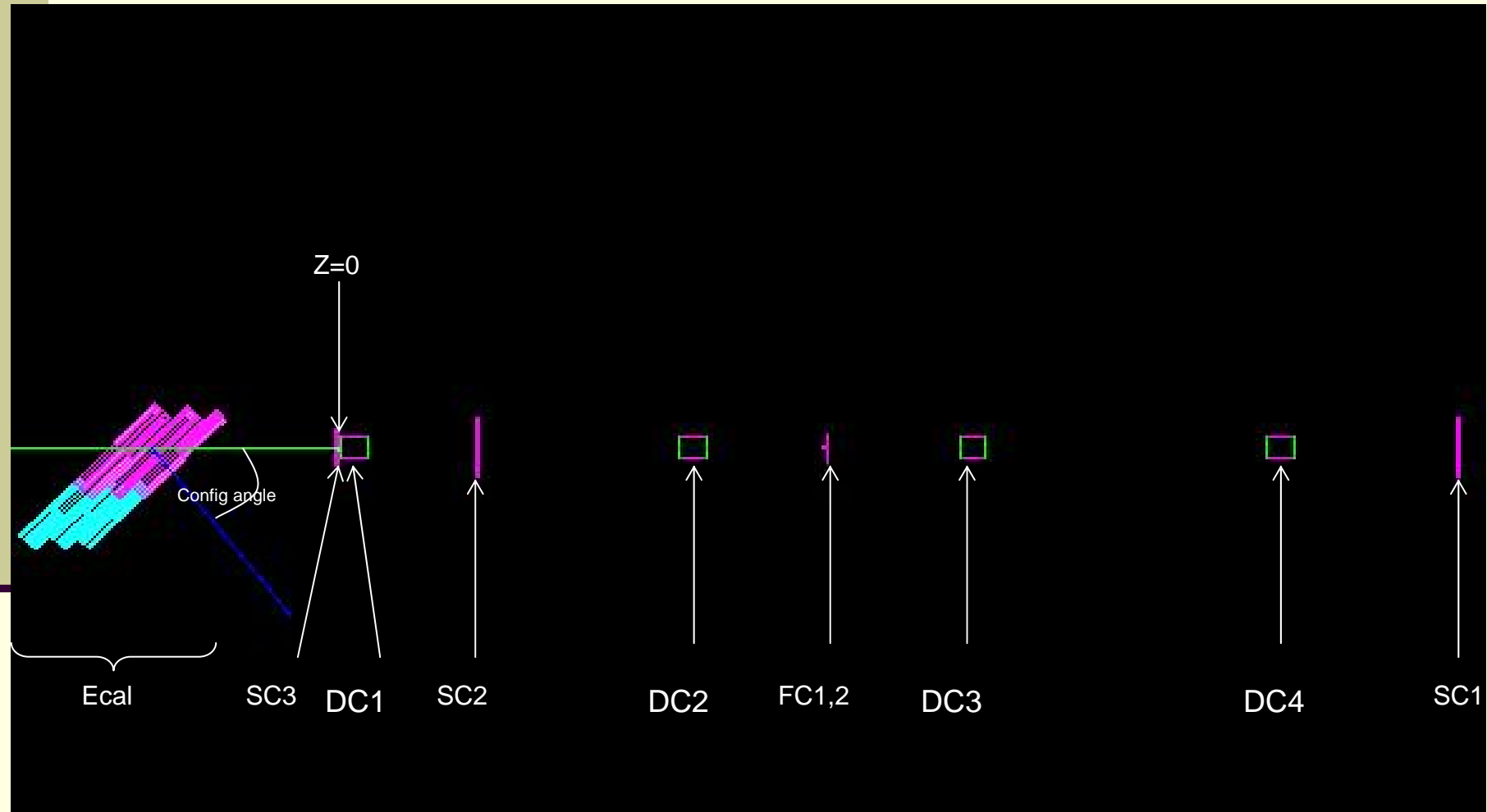
All distances are in mm

## ‘Old’ coord. syst. Vs ‘New’ coord. syst.

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- In ‘old’ coordinate system the axes are tied to the ECAL, therefore when the ECAL is simulated at an angle  $\theta$  wrt beam normal incidence, the ECAL is kept fixed and all beam detectors are rotated by  $-\theta$  wrt the ECAL front face
  - Not intuitive !
- In new coordinate system the axes are not tied to the ECAL, so rotation is done keeping fixed the beam detectors and rotating the ECAL only
  - See next slide !

# TBDesy0506\_01 with ECAL @ 45°



# Improvements in simulation wrt Mokka 06-03p01

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- **Real drift chambers** in the **Desy** setup give **separate measurement of X and Y position on hits**
  - **Fist half of the chamber gives X position, second half gives Y position**
- As chambers are simulated in **Mokka v06-03p01**, **each hit has an X and Y position**
  - **Re-write driver** to match real chambers as much as possible
- At the **digitization stage**, we would like to use **drivers that are independent of the setup (Desy or CERN)**
  - Need to write **one single collection of hits** instead of **one collection per chamber**

# New DCH driver for Desy0506 model

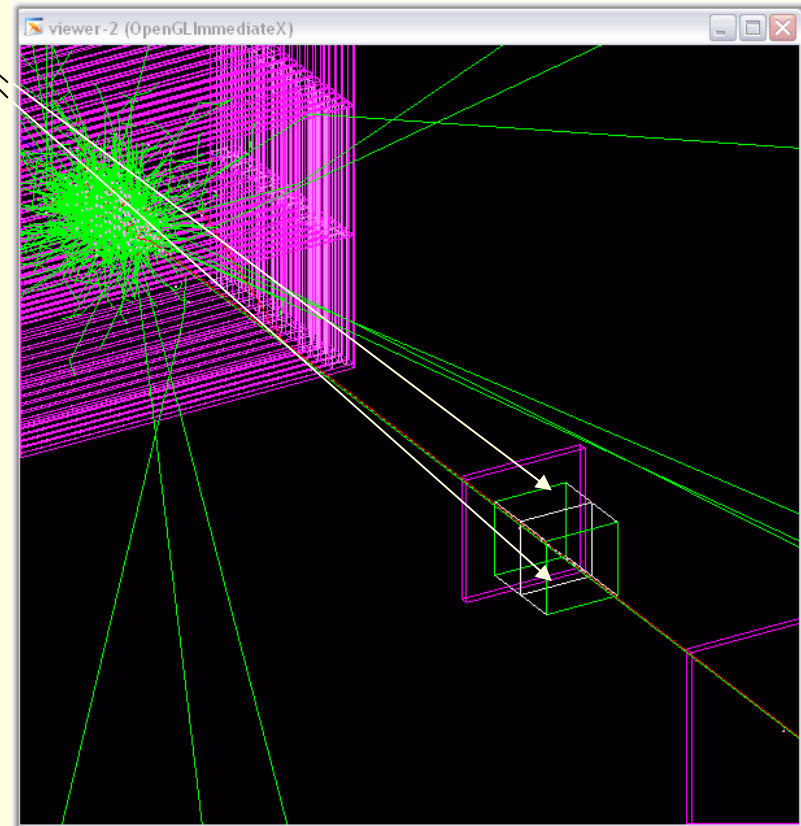
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- **New DCH driver** has been tested
  - Each chamber is built assuming **two different gas volumes** (one for X and one for Y)
  - Hits in each gas volume are **simulated as TRKHit** (==SimTrackerHit in LCIO)
    - (x,y,z) **postion** of hit is generated
    - Digi code will have to **consider the appropriate coordinate** (x or y) depending on the layer
  - Total of **8 layers (2Xchambers)**
  - New test beam model **implemented in the DB**
    - **TBDesy0506\_dchxy\_new**



# New chamber layout

- Two separate volumes
- One single hit collection
  - TBdchXY02\_dchSDxy0
  - Use cellID to distinguish hits from each layer:
    - DC1 -> layer 0 (X), 1 (Y)
    - DC2 -> layer 2 (X), 3 (Y)
    - DC3 -> layer 4 (X), 5 (Y)
    - DC4 -> layer 6 (X), 7 (Y)



# Conclusions

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- **Models for detailed simulations** of the 2006 test beam setup are available
- **Several models** are implemented in latest version of Mokka (06-03p02)
  - 'Old' coordinate system
    - TBDesy0506, TBcern0806, TBCern1006
  - 'New' coordinate system
    - TBDesy0506\_01, TBCern0806\_01, TBDesy1006\_01
  - New DCH layout, with one collection of hits
    - TBDesy0506\_dchxy\_new
  - Looking into more possible improvements
    - Simulation of steel frame around scintillators (Desy/CERN)
    - Improvement in simulation of CERN DCHs
- All info on detector models can be found on the Mokka WEB page:
  - <http://polywww.in2p3.fr:8081/MOKKA/detector-models/test-beams/test-beams/>