



# A MAPS-based digital Electromagnetic Calorimeter for the ILC

Anne-Marie Magnan  
Imperial College London

on behalf of the MAPS group:

Y. Mikami, N.K. Watson, O. Miller, V. Rajovic, J.A. Wilson  
(University of Birmingham)

J.A. Ballin, P.D. Dauncey, A.-M. Magnan, M. Noy  
(Imperial College London)

J.P. Crooks, M. Stanitzki, K.D. Stefanov, R. Turchetta, M. Tyndel, E.G. Villani  
(Rutherford Appleton Laboratory)

## Context of this R&D

### I. Introduction to MAPS

What is **MAPS** ?

Why for an **Electromagnetic CAL**orimeter ?

### II. The current **sensor** layout

### III. Sensor simulation

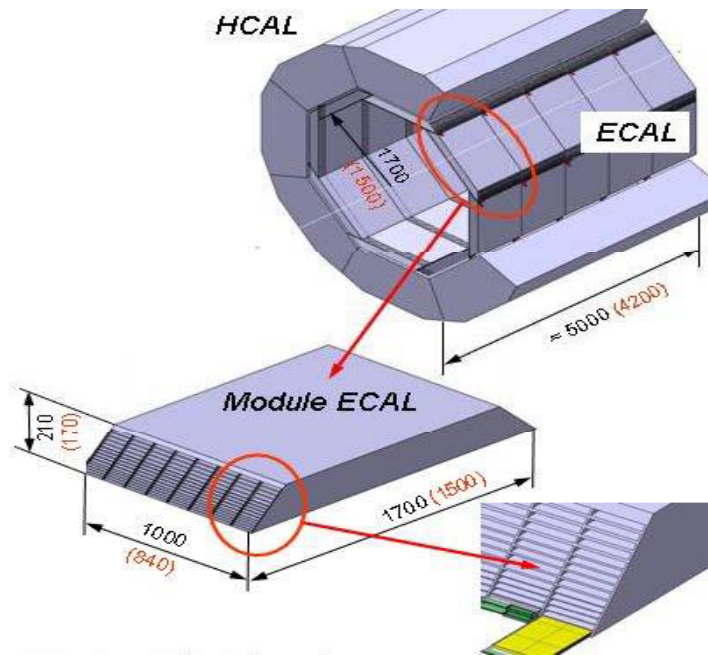
### IV. Physics simulation

**digitisation** procedure

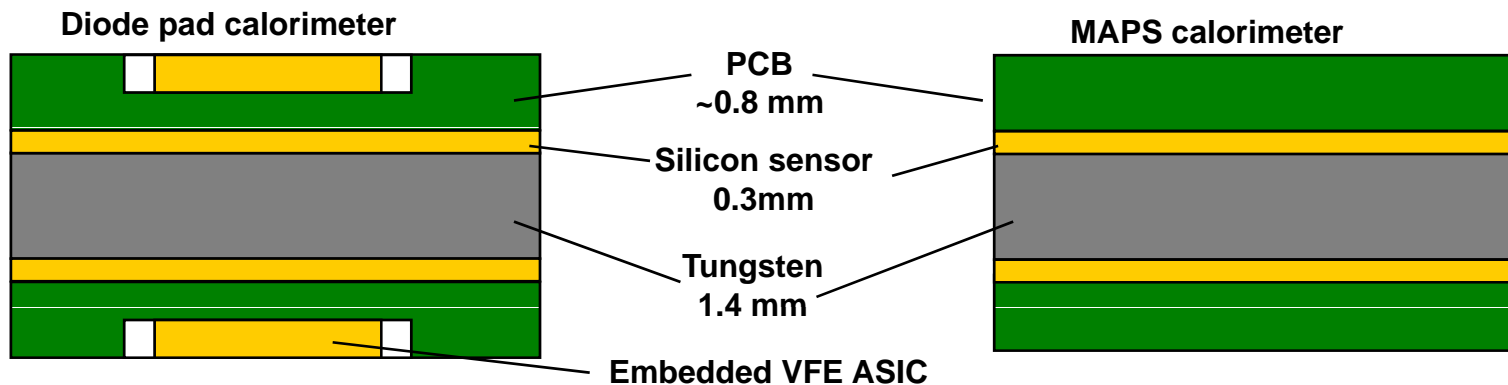
influence of parameters on the **energy resolution**

## Conclusion

# Context of this R&D

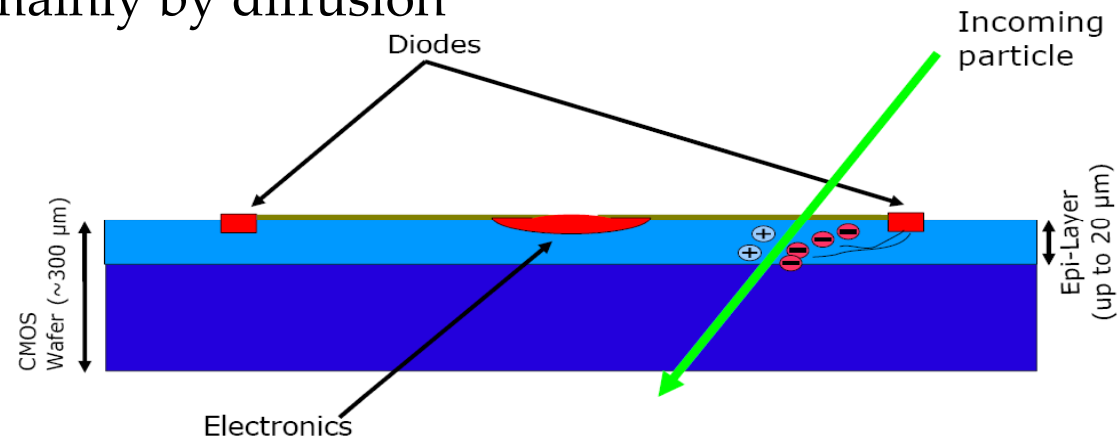


- Alternative to CALICE Si/W analogue ECAL
- No specific detector concept
- “Swap-in” solution leaving mechanical design unchanged



# Introduction to MAPS

- **MAPS ? Monolithic Active Pixel Sensor**
  - ✓ CMOS technology, in-pixel logic: **pixel=sensor+readout electronics**
  - ✓ **50x50  $\mu\text{m}^2$**  : reduces probability of multiple hit per pixel
  - ✓ Collection of charge mainly by diffusion



- **Why for a calorimeter ?**

## high granularity :

- ☺ better position resolution → potentially better PFA performances,
- ☺ or detector more compact → reduced cost
- ☺ ☹  $10^{12}$  pixels : digital readout, DAQ rate dominated by noise
- ☹ Area needed for logic and RAM : ~10% dead area

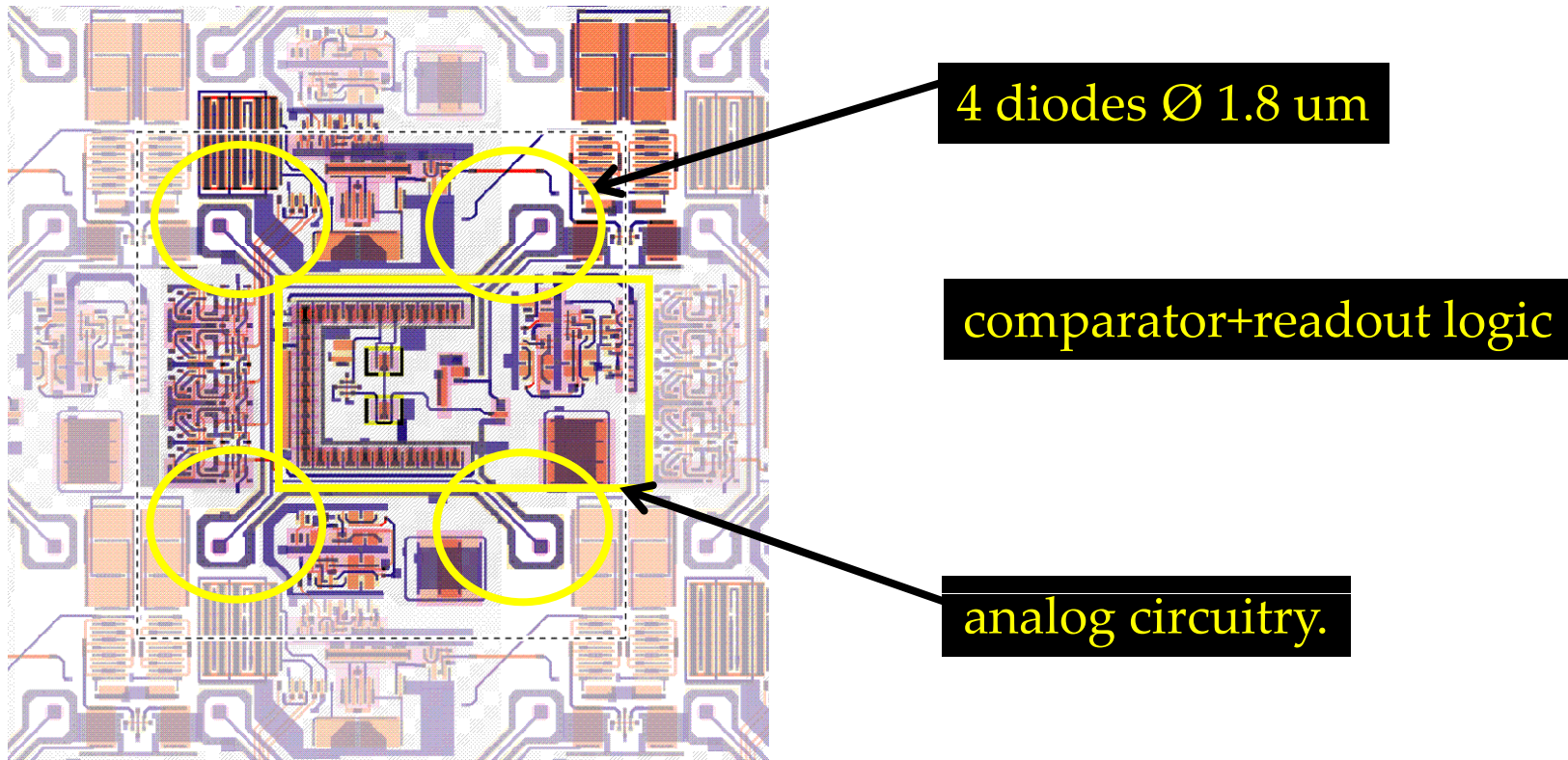
Cost saving : ☺ CMOS vs high resistivity Si wafers

Power dissipation : ☺ more uniform

☹ challenge to match analog ECAL  $1 \mu\text{W}/\text{mm}^2$

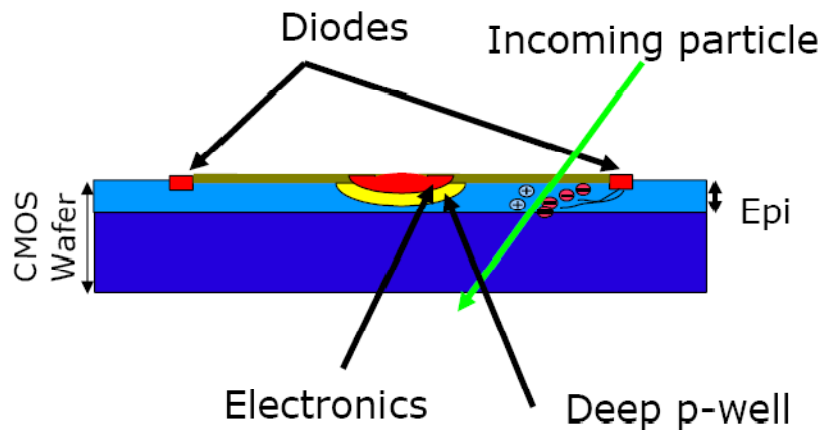
# Sensor layout : v1.0 submitted !

Design submitted April 23rd, with several architectures.  
One example:

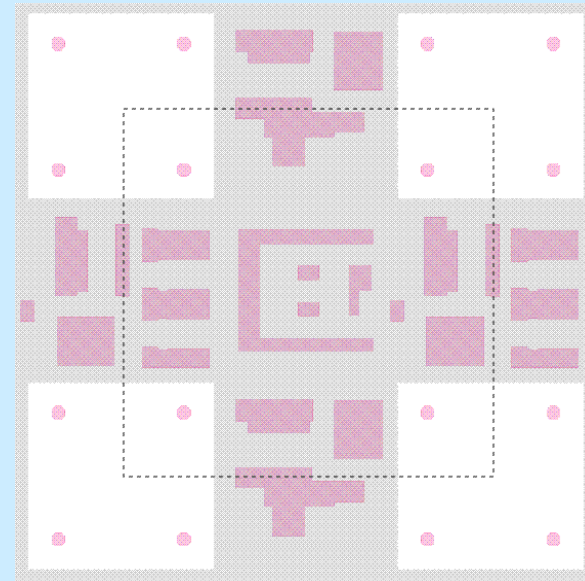


# What's eating charges : the N-well and P-well distribution in the pixels

- Electronics N-well absorbs a lot of charge : possibility to isolate them ?
- INMAPS process : deep P-well implant 1  $\mu\text{m}$  thick everywhere under the electronics N-well.

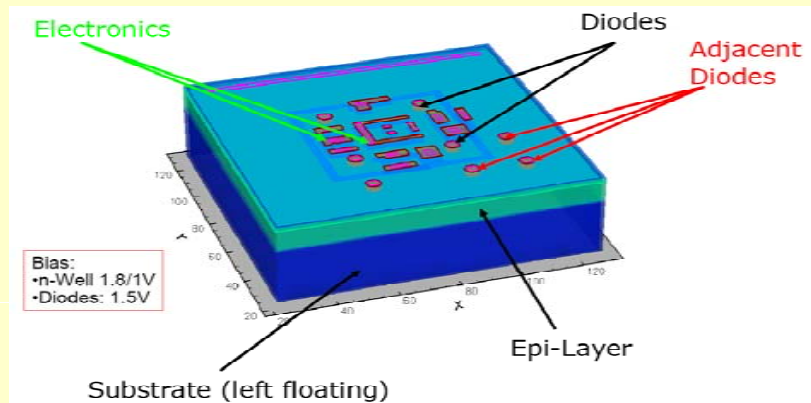


pink = nwell (eating charge)  
blue = deep p-well added to block the charge absorption  
INMAPS process



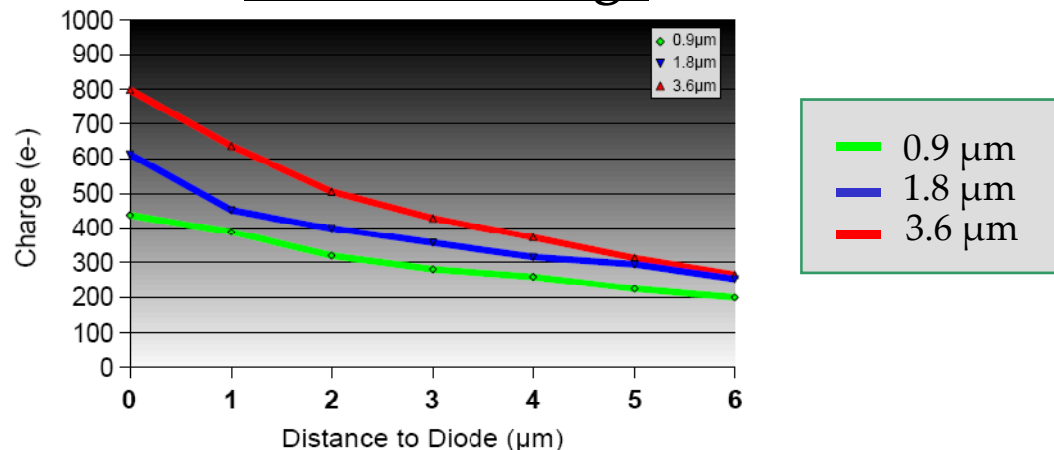
# The sensor simulation setup

Using Centaurus TCAD for sensor simulation + CADENCE GDS file for pixel description

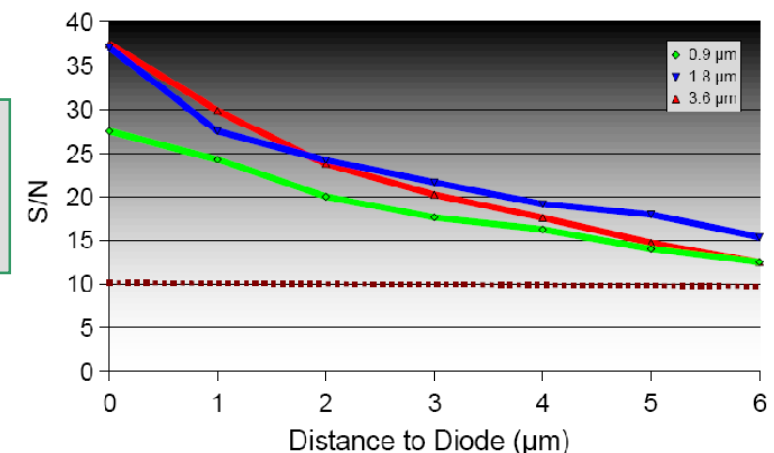


- Diode size has been optimised in term of signal over noise ratio, charge collected in the cell in the worse scenario (hit at the corner), and collection time.
- Diodes place is restricted by the pixel designs, e.g. to minimise capacitance effects

## Collected charge

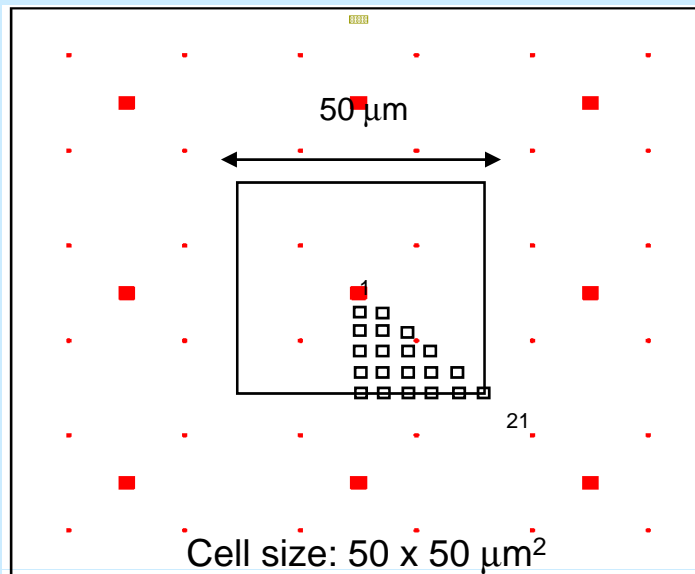


## Signal over noise

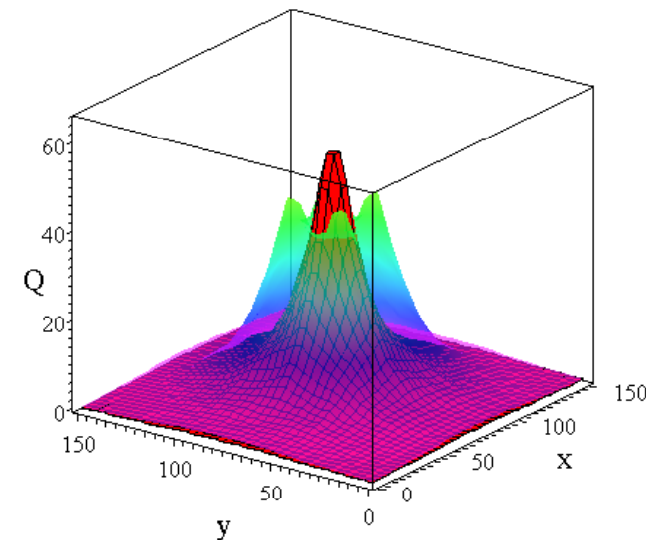


# Fast simulation for Physics analysis

Preliminary results obtained assuming perfect P-well : to reduce the computational time, no N-well or P-well are simulated. Will be compared to a pessimistic scenario with no P-well but a central N-well eating half of the charge.



Whole 3\*3 array with neighbouring cells is simulated, and the initial MIP deposit is inputted on 21 points (sufficient to cover the whole pixel by symmetry)



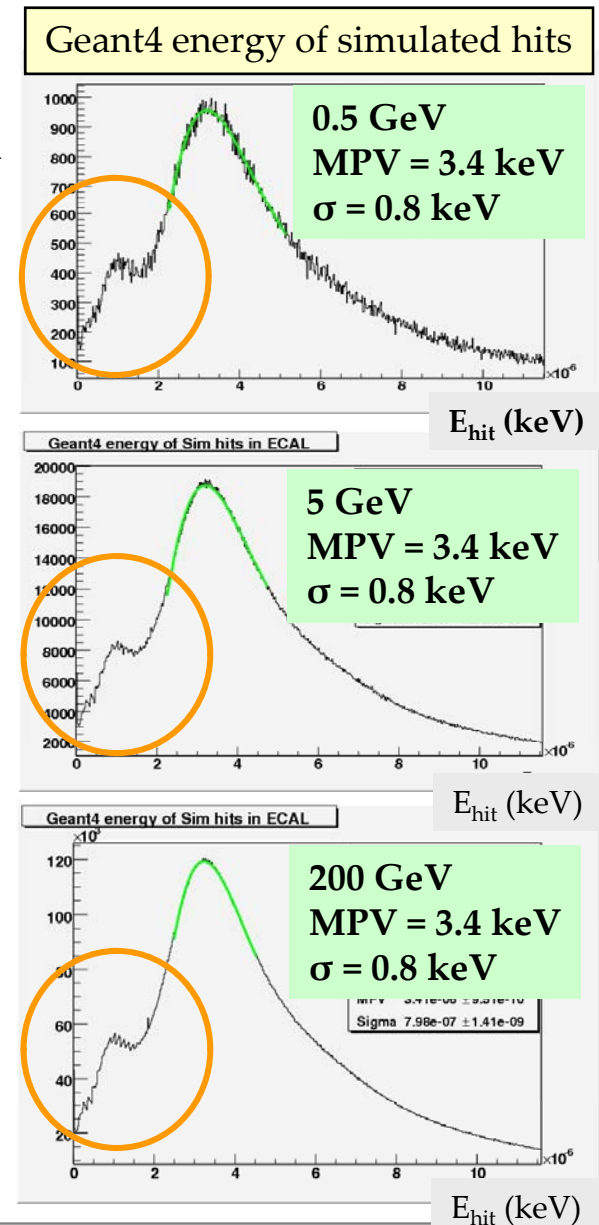
Example of pessimistic scenario of a central N-well eating half of the charge



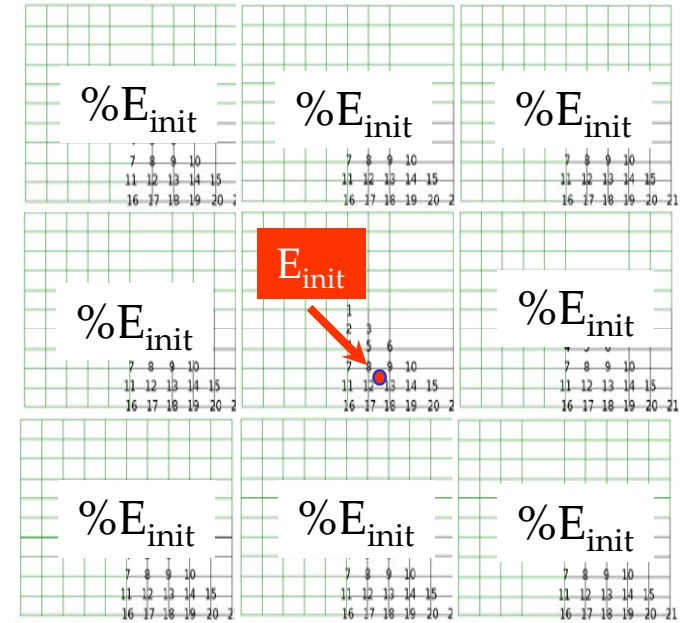
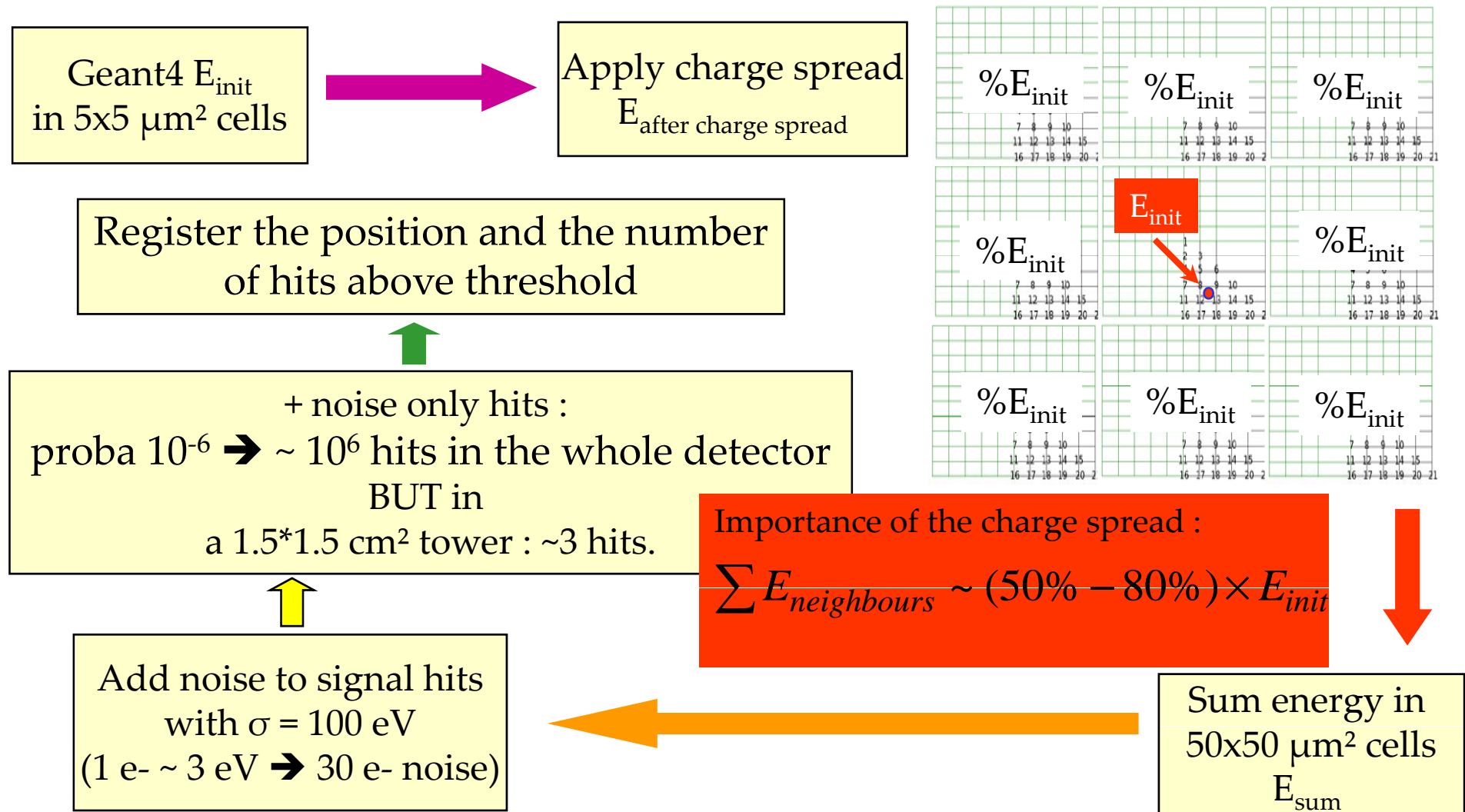
# Physics simulation

- MAPS Simulation implemented in MOKKA, with LDC01 for now on.
- MIP landau MPV stable vs energy @ Geant4 level  
 → Assumption of 1 MIP per cell checked up to 200 GeV,
- Definition of energy :  $E \propto N_{MIPS}$ .
- Binary readout : need to find the optimal threshold, taking into account a  $10^{-6}$  probability for the noise to fluctuate above threshold.
- **MIP crossing boundaries** : effect can be reduced by clustering
- So energy resolution is given by the distribution of hits/clusters above threshold:

$$\frac{\sigma_E}{E} \propto \frac{\sqrt{\sigma_{N_{pixels}}^2 + N_{noise}}}{N_{pixels}}$$

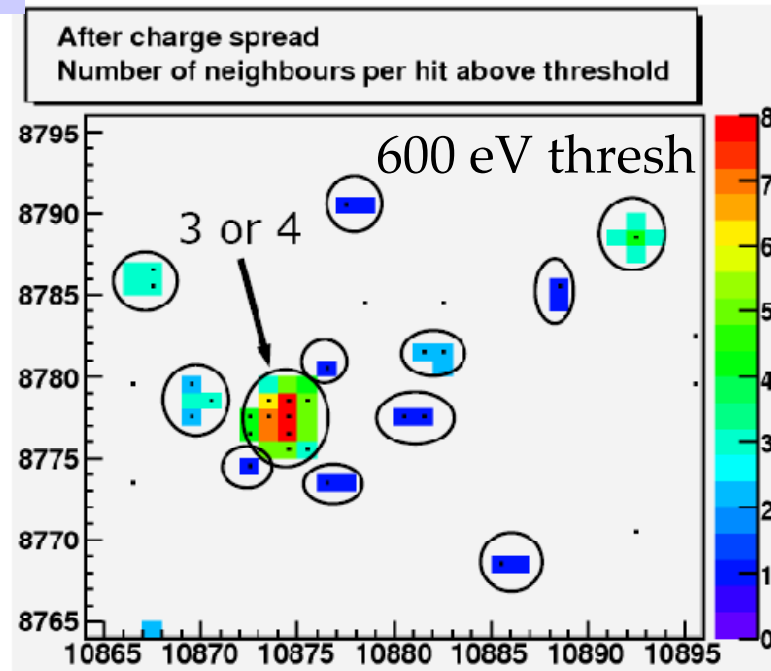
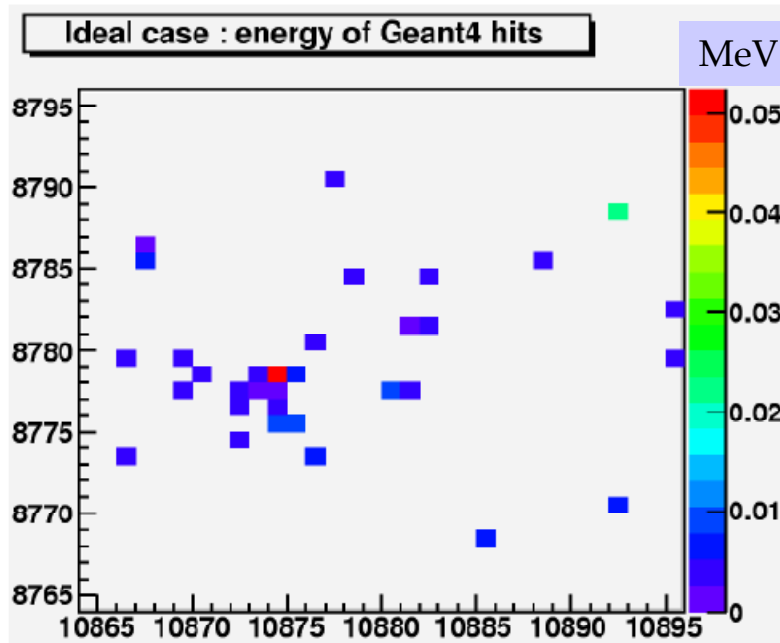


# Digitisation procedure



# Simple clustering

## A particular event, a particular layer



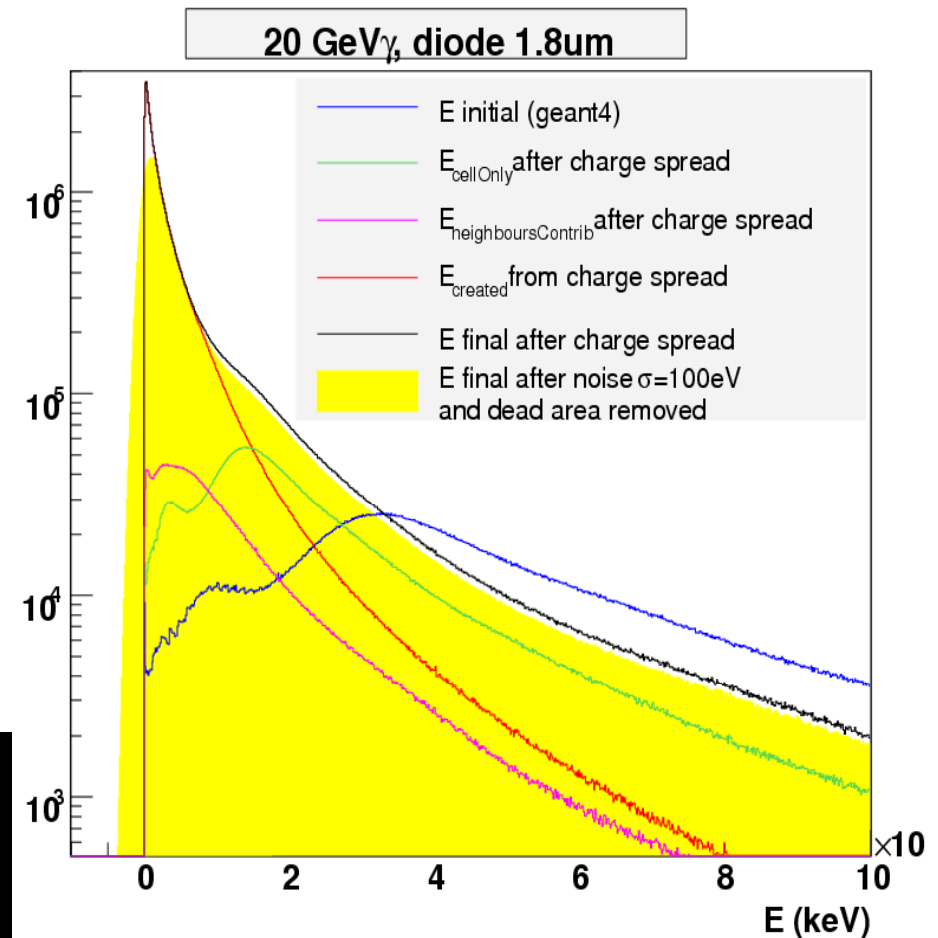
- Loop over hits classified by number of neighbours :
- if  $< 8$  : count 1 (or 2 for last 10 layers) and discard neighbours,
- if 8 and one of the neighbours has also 8 : count 2 (or 4) and discard neighbours.
- Not very optimised : lots of room for improvement !

# How is the energy affected by each digitisation step ?

- E initial : geant4 deposit
- What remains in the cell after charge spread assuming perfect P-well
- Neighbouring hit:
  - hit ? Neighbour's contribution
  - no hit ? Creation of hit from charge spread only
- All contributions added per pixel

• + noise  $\sigma = 100$  eV

• + noise  $\sigma = 100$  eV, minus dead areas :  
5 pixels every 42 pixels in one direction



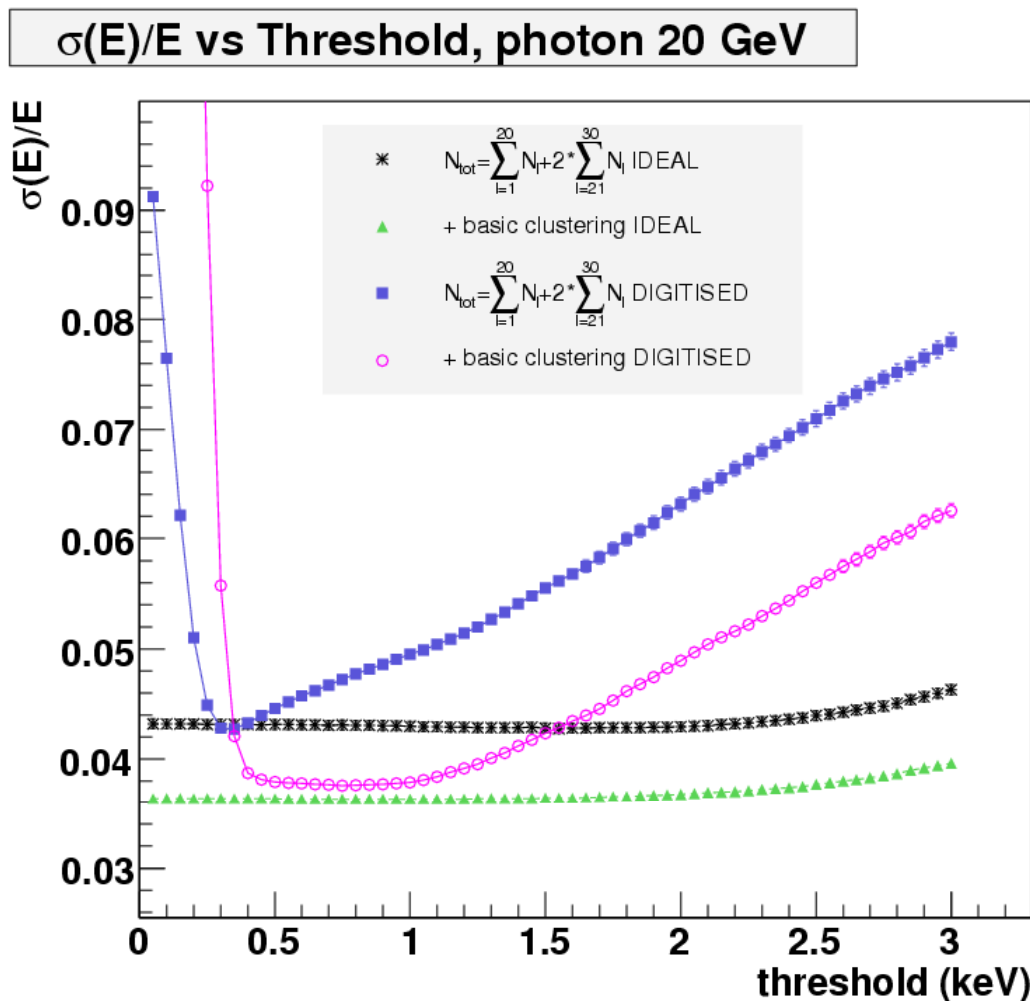
# Effect of the clustering on the energy resolution

IDEAL : Geant4 energy,

- ✓ no charge spread,
- ✓ no noise,
- ✓ dead area removed (5 pixels every 42 pixels in one direction)
- ✓ without or **with clustering**

DIGITIZED:

- ✓ charge spread with perfect P-well assumed,
- ✓ noise  $\sigma=100$  eV,
- ✓  $10^{-5}$  probability of a pixel to be above threshold
- ✓ dead area removed
- ✓ without or **with clustering**



# Effect of charge spread model

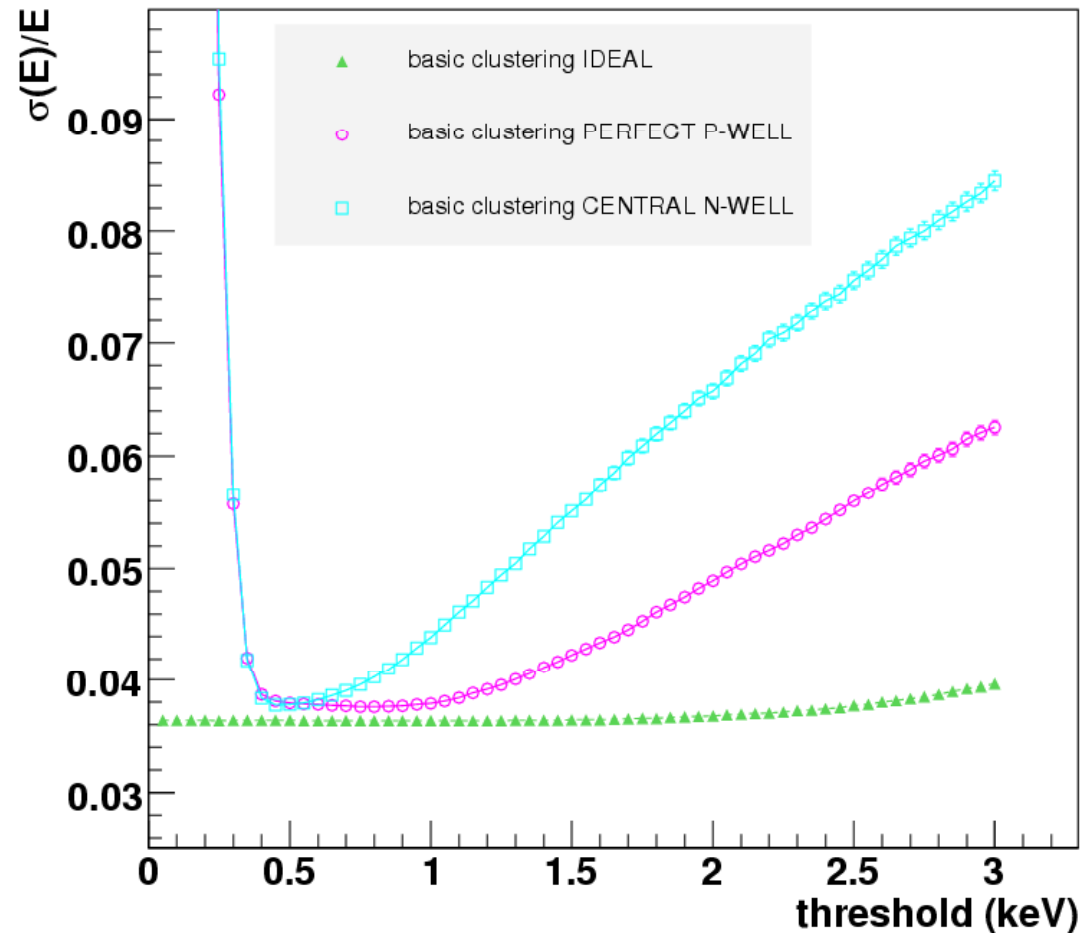
Optimistic scenario:

Perfect P-well after clustering: large minimum plateau  $\rightarrow$  large choice for the threshold !!

Pessimistic scenario:

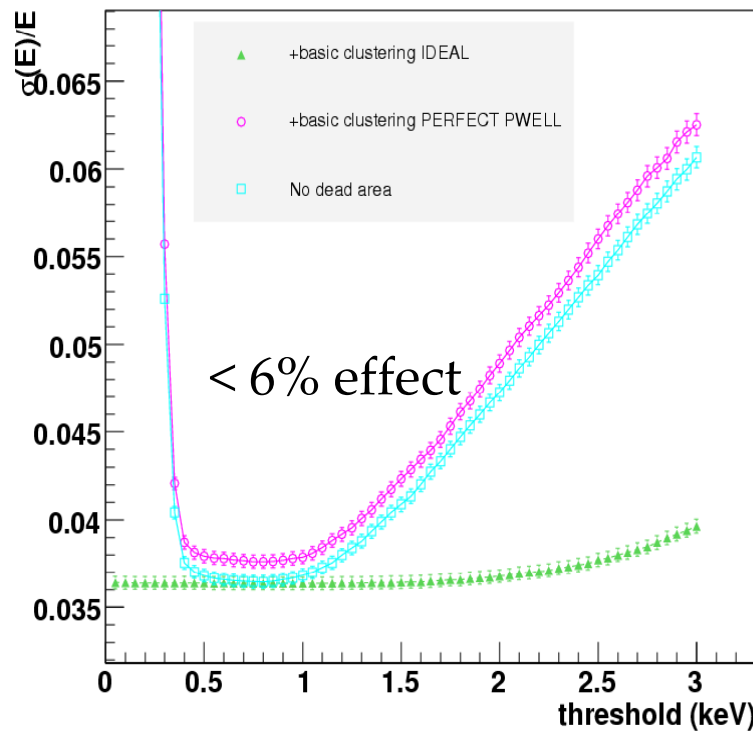
Central N-well absorbs half of the charge, but minimum is still in the region where noise only hits are negligible + same resolution !!!

$\sigma(E)/E$  vs Threshold, photon 20 GeV

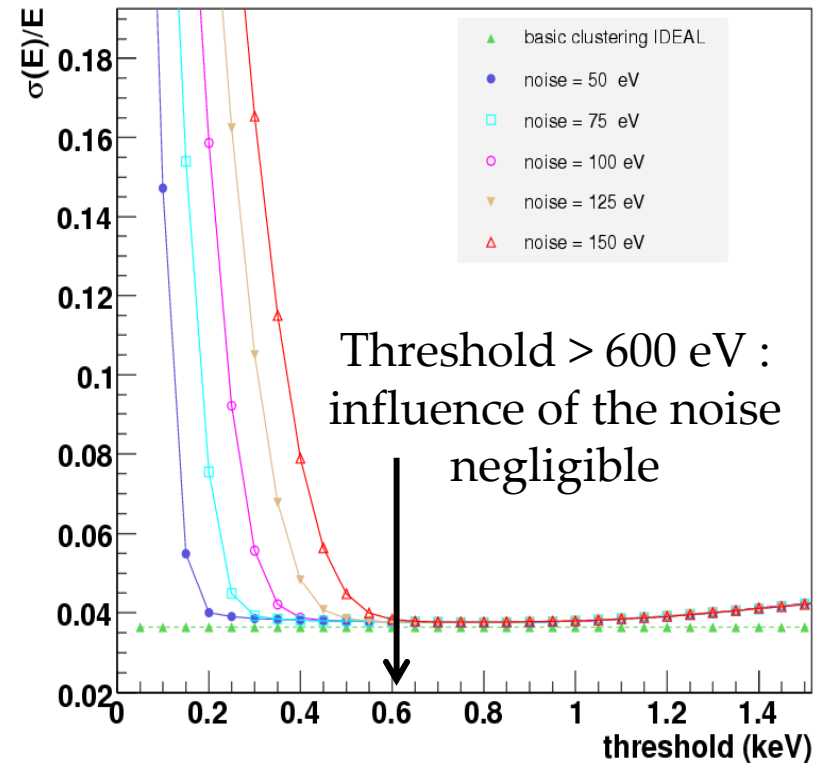


# Effect of dead area and noise after clustering

$\sigma(E)/E$  vs Threshold, photon 20 GeV



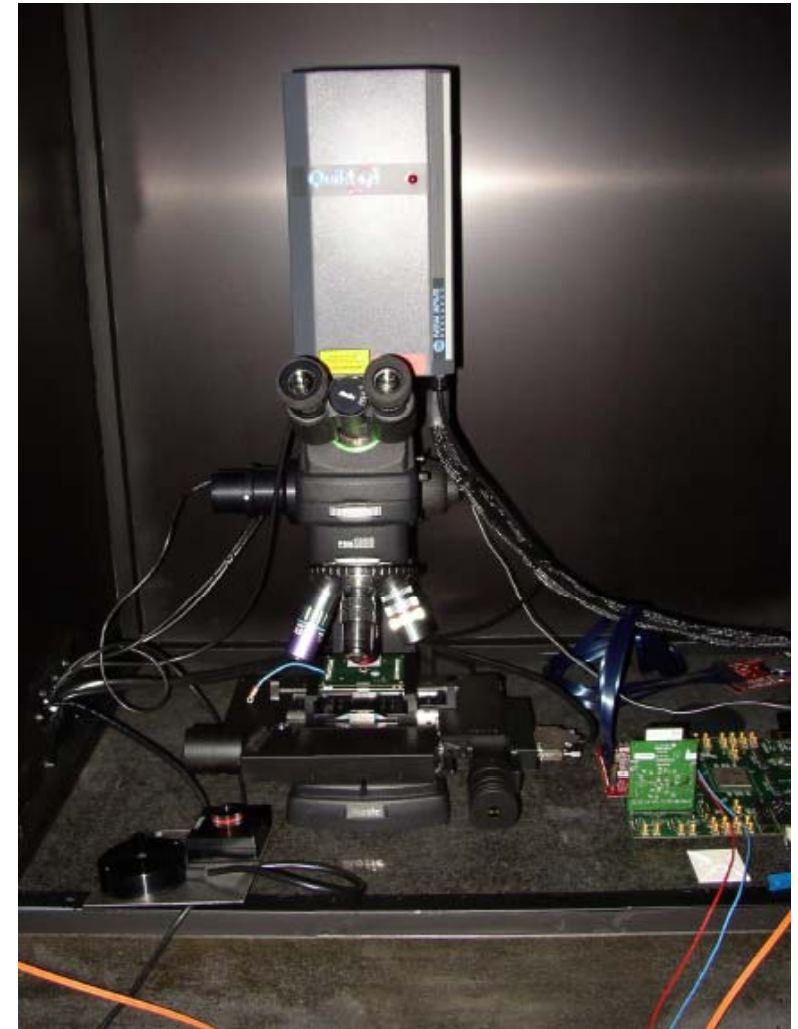
$\sigma(E)/E$  vs Threshold, photon 20 GeV



→ energy resolution dependant on a lot of parameters : need to measure the noise and the charge spread ! And improve the clustering, especially at high energy.

# Plans for the summer

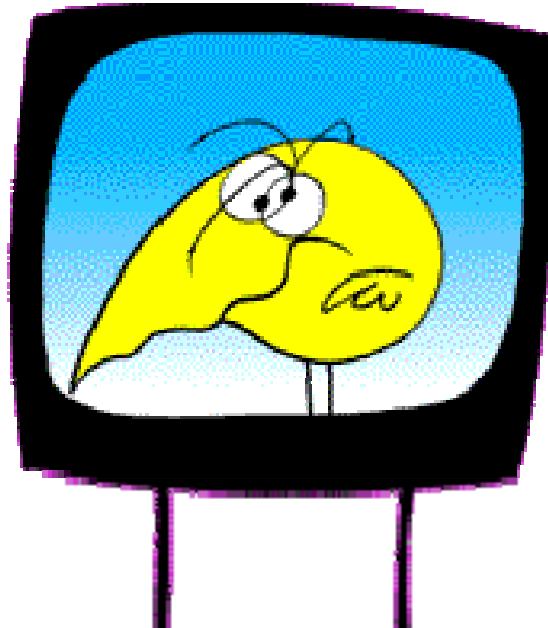
- Sensor has been submitted to foundry on April 23rd, back in July.
- Charge diffusion studies with a powerful laser setup at RAL :
  - 1064, 532 and 355 nm wavelength,
  - focusing  $< 2 \mu\text{m}$ ,
  - pulse 4ns, 50 Hz repetition rate,
  - fully automatized
- Cosmics and source setup to provide by Birmingham and Imperial respectively.
- Work ongoing on the set of PCBs holding, controlling and reading the sensor.
- possible beam test at DESY at the end of this year.





# Conclusion

- Sensor v1.0 has been **submitted**. We aim to have first **results in the coming months!**
- Test are mandatory to **measure** the sensor **charge spread** and **noise** for digitisation simulation.
- Once we trust our simulation, detailed physics simulation of **benchmark processes** and **comparison with analog ECAL design** will be possible.



*Thank you for your attention*

# Sensor layout : v1.0 submitted !

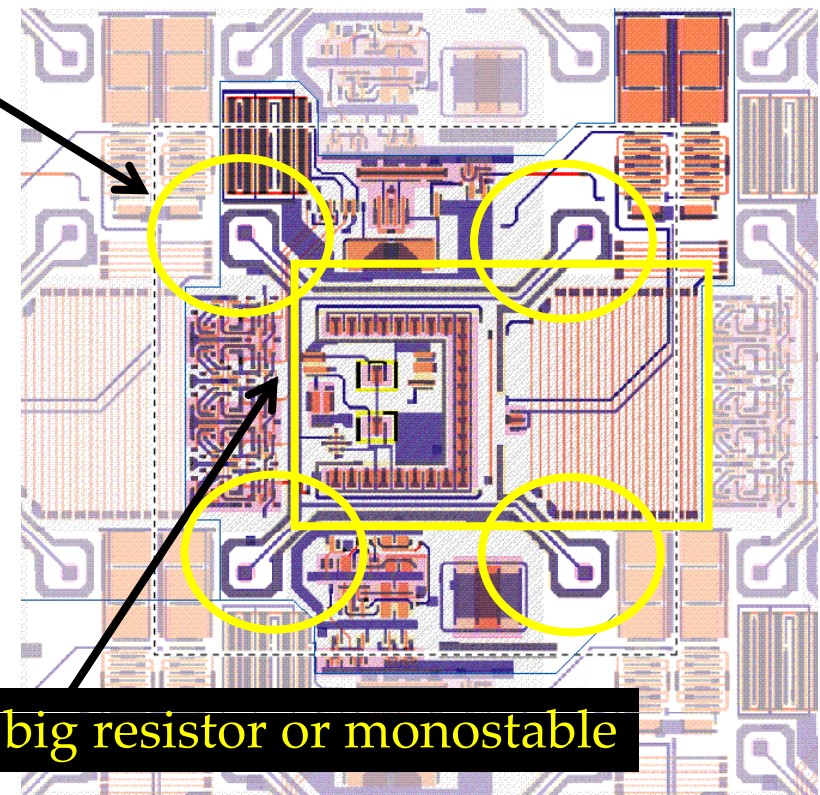
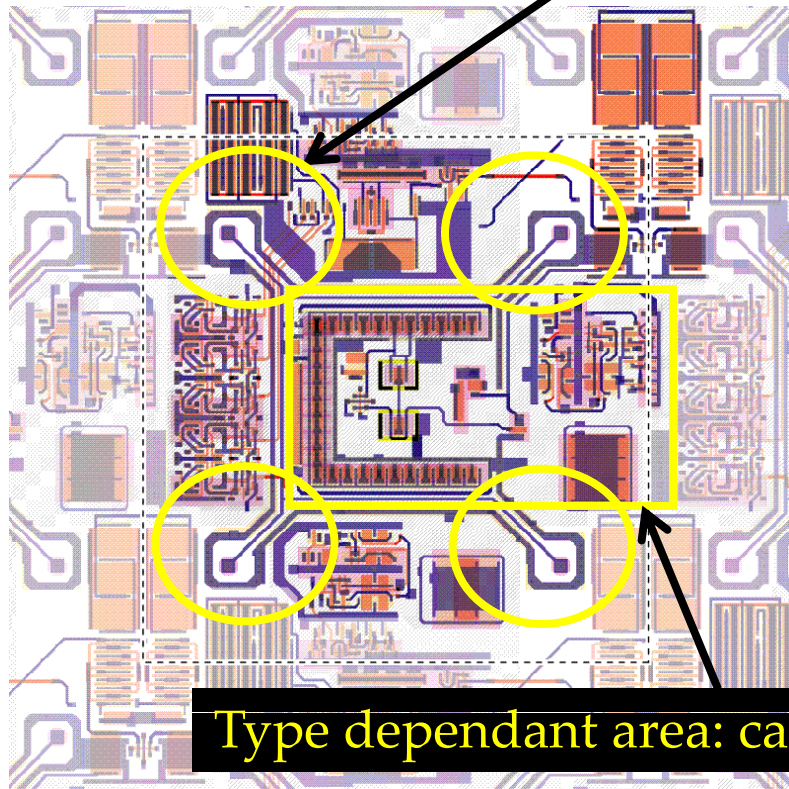
Design submitted April 23rd :

Presampler

Preshaper

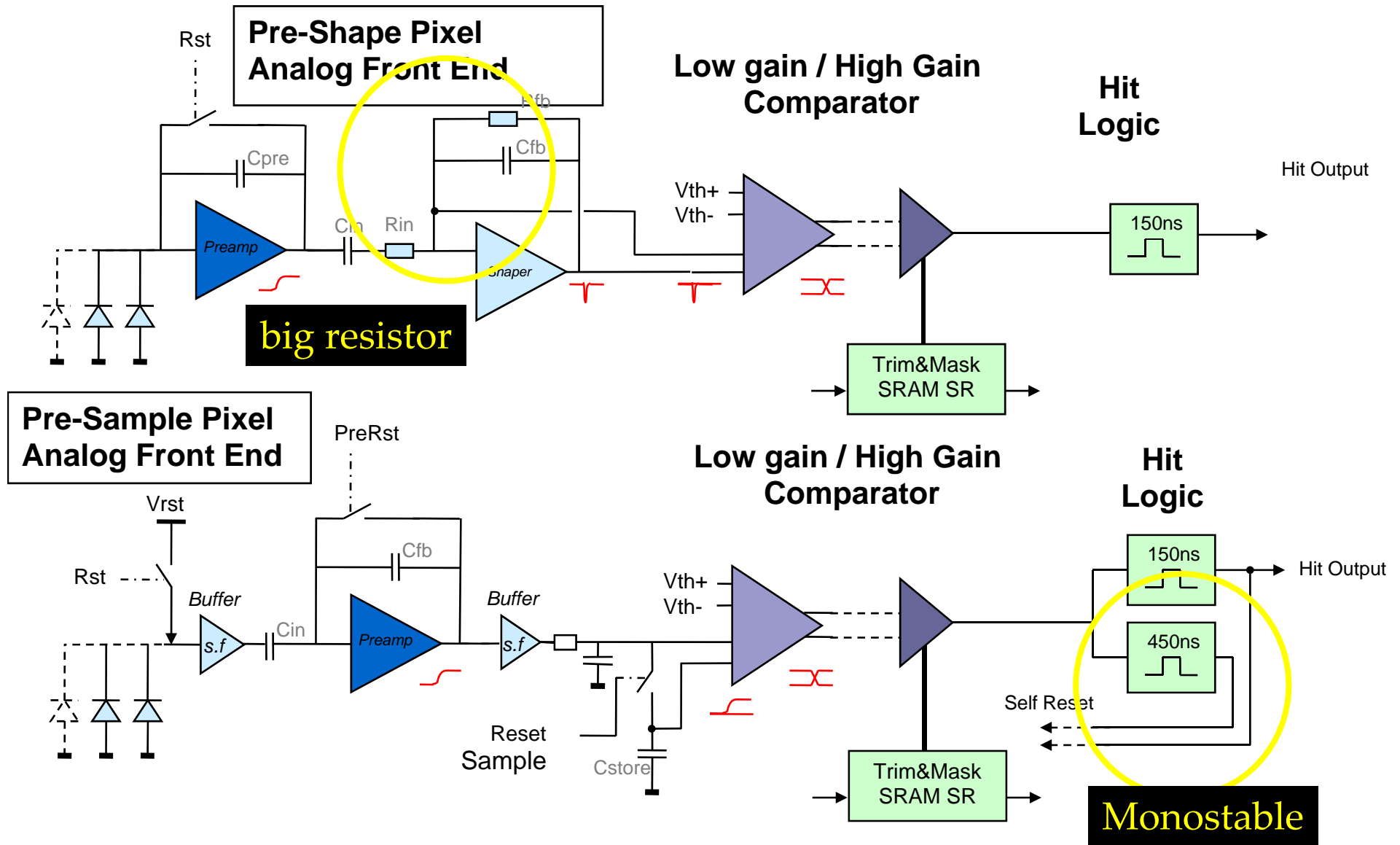
4 diodes  $\varnothing$  1.8  $\mu$ m

same comparator+readout logic



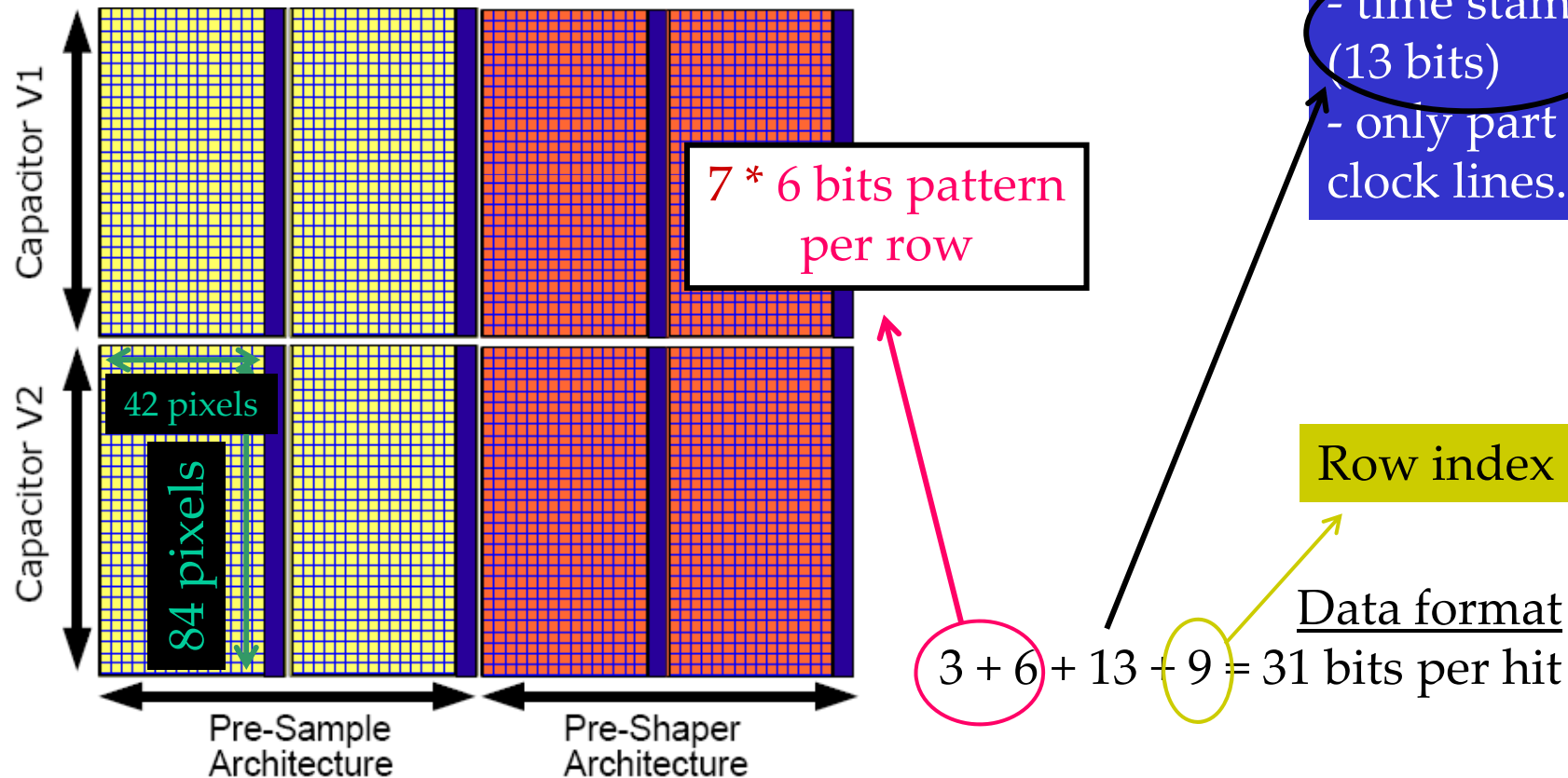
Type dependant area: capacitors, and big resistor or monostable

# THE DesignS



# The sensor test setup

1\*1 cm<sup>2</sup> in total  
 2 capacitor arrangements  
 2 architectures  
 6 million transistors, 28224 pixels

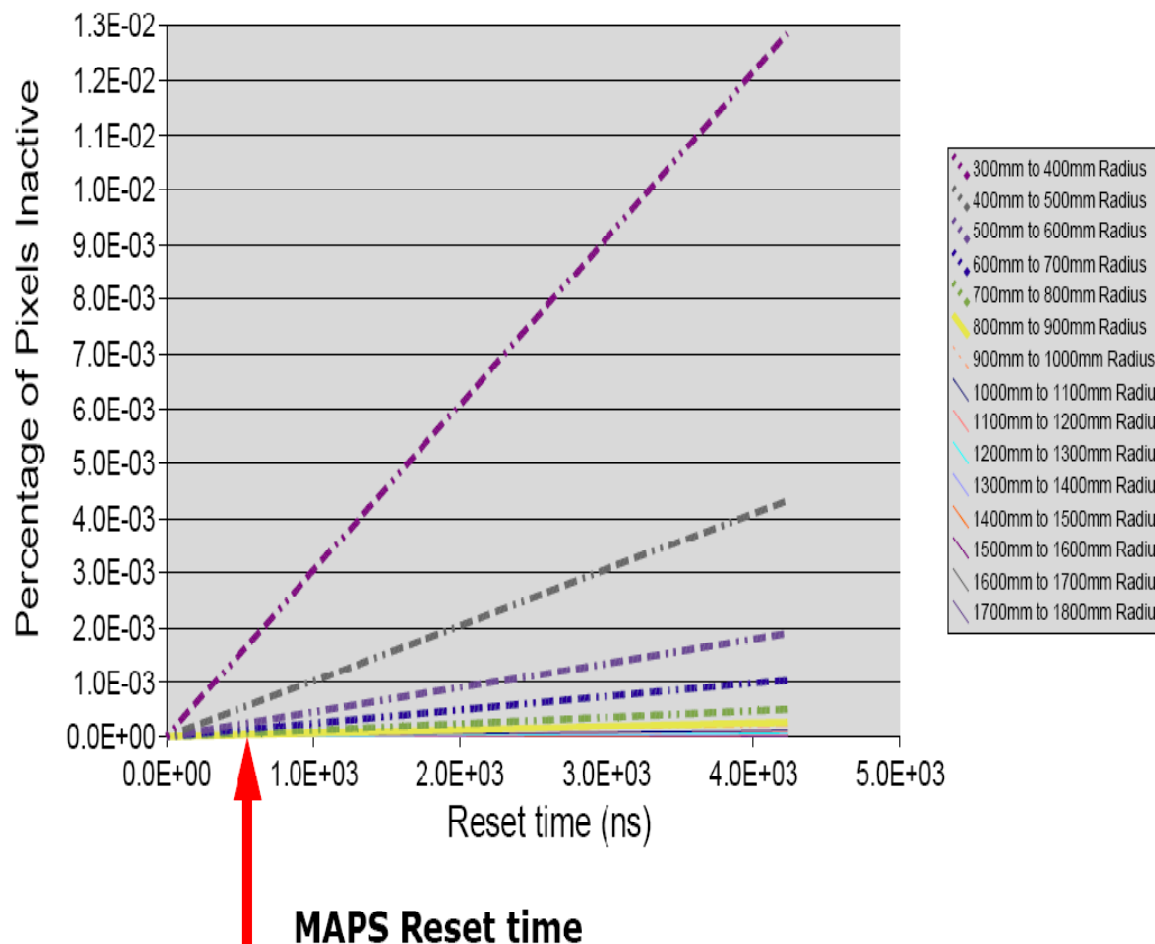
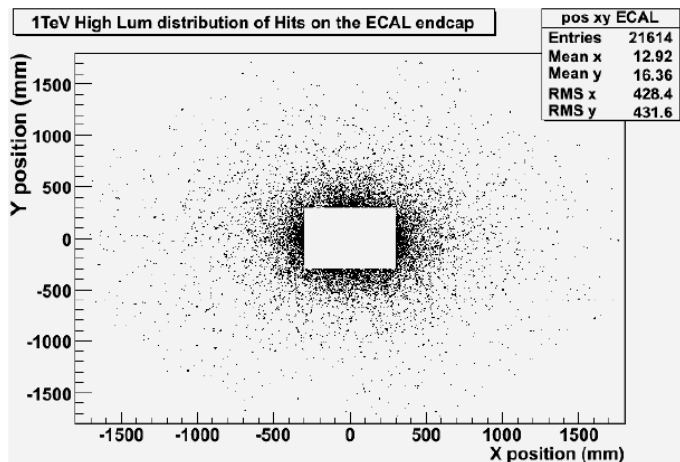


5 dead pixels for logic :  
 -hits buffering (SRAM)  
 - time stamp = BX (13 bits)  
 - only part with clock lines.

# Beam background studies

- Done using GuineaPig
- 2 scenarios studied :
  - 500 GeV baseline,
  - 1 TeV high luminosity.

purple = innermost endcap radius  
 500 ns reset time → ~ 2‰ inactive pixels



# Particle Flow: work started !

- Implementing PandoraPFA from Mark Thomson : now running on MAPS simulated files.
- **First plots** with  
Z→uds @ 91 GeV in ECAL barrel gives a resolution of  $35\% / \sqrt{E}$  before digitisation and clustering

