Digital ECAL: Lecture 3

Paul Dauncey, Imperial College London

DECAL lectures summary

- Lecture 1 Ideal case and limits to resolution
 - Digital ECAL motivation and ideal performance compared with AECAL
 - Shower densities at high granularity; pixel sizes
 - Effects of EM shower physics on DECAL performance
- Lecture 2 Status of DECAL sensors
 - Basic design requirements for a DECAL sensor
 - Current implementation in CMOS technology
 - Characteristics of sensors; noise, charge diffusion
 - Results from first prototypes; verification of performance
- Lecture 3 Detector effects and realistic resolution
 - Effect of sensor characteristics on EM resolution
 - Degradation of resolution due to sensor performance
 - Main issues affecting resolution
 - Remaining measurements required to verify resolution

DECAL lectures summary

- Lecture 1 Ideal case and limits to resolution
 - Digital ECAL motivation and ideal performance compared with AECAL
 - Shower densities at high granularity; pixel sizes
 - Effects of EM shower physics on DECAL performance
- Lecture 2 Status of DECAL sensors
 - Basic design requirements for a DECAL sensor
 - Current implementation in CMOS technology
 - Characteristics of sensors; noise, charge diffusion
 - Results from first prototypes; verification of performance
- Lecture 3 Detector effects and realistic resolution
 - Effect of sensor characteristics on EM resolution
 - Degradation of resolution due to sensor performance
 - Main issues affecting resolution
 - Remaining measurements required to verify resolution

Detector effects

- Lecture 1 showed that a DECAL with 50µm pixels has potential to give good linearity and resolution
- Lecture 2 showed we can characterise the TPAC1 sensor performance
- Now put the two together to show realistic resolution
 - Assume a whole ECAL made from TPAC1-like sensors
- Must include the effects of
 - Noise
 - Charge diffusion between pixels
 - Dead areas

Basic epitaxial layer energy deposits

- A MIP creates ~80 electronhole pairs in silicon per 1µm
 - Equivalently, deposits energy with dE/dx ~ 300eV/µm
- Passing through 12µm of the epitaxial layer at normal incidence leaves an average of ~1000e⁻ signal charge
 - Equivalently, deposits a total of ~3.6keV
- Noise is ~20e⁻
 - Equivalent to ~70eV deposit



Effect of diffusion; example layer



Effect of diffusion



Effect of diffusion on signal charge

- Original charge (energy) deposited in hit pixel
- Remaining charge in hit pixel after diffusion
- Charge diffused into hit pixels from neighbours
- Charge diffused into non-hit pixels
- Total charge distribution
- Total distribution including noise



Effect of threshold



Compare with original particles



- Single particle can result in ~1-4 pixels being above threshold
 - All neighbouring
 - Call each isolated group a "cluster"
 - Count clusters not pixels to estimate particle number
 - **PROBLEM**: close-by particles give larger clusters
 - Estimate particles in a cluster by 1+N₈
 - N_8 = number of pixels with all 8 neighbours also hit













Efficiency for MIPs

- Expect ~95% efficiency
- Perfectly OK for a DECAL
- Not so good for a tracker!



Resolution effect of noise

- Choosing threshold ~500eV gives same resolution as with no noise
 - Close to ideal resolution of Lecture 1: ~10% worse
- Following plots with noise of 120eV
 - Pessimistic: actual measured noise is 70eV



Resolution effect of charge diffusion

- With no charge diffusion, signal is ~3 times bigger; threshold cut has almost no effect over this range
- With charge diffusion and correct threshold, resolution is only slightly degraded
- Small disagreements of charge diffusion modelling not significant



Resolution with and without deep p-well



- Without deep p-well, a lot of charge is lost to circuit n-wells
 - Average signal is ~25% of deep p-well case

Resolution with and without deep p-well

- Without deep p-well, approximately only ¼ of number of pixel hits seen
- Contributes as √N so gives factor of two worse resolution
- Deep p-well essential



Resolution effect of dead areas



- Small frequent dead areas reduce the number of pixels hit for all showers by the same amount
- Gives √N fluctuations to all showers



- Large infrequent dead areas lose many hits for some showers and none for others
- Gives big fluctuations for some fraction of showers

Resolution effect of dead areas

- Dead memory storage pixels on TPAC1 give 11% dead area
 - Strips of 250µm wide
 - One strip every 2.35mm
- Small(ish) compared to EM shower so goes as √N
 - ~5% degradation
- Also shown is 15% dead area
 - Includes estimates 4% extra dead area from sensor edges



Resolution effect of clustering

- Charge diffusion means one MIP can (usually) give between 1 and 4 pixel hits
 - Ruins resolution if counting pixels with no clustering
- Basic clustering using 1+N₈ essential to achieve good resolution
- Scope to play with clustering algorithms and improve further?



Effect on Particle Flow?



Remember...

- Most of this is purely simulation
 - Almost definitely wrong!
- Could be many "real detector" problems not yet found; we have heard about
 - Guard rings, temperature dependence, fibre-PMT alignment, sparking, electromagnetic pickup, etc, etc...
 - We don't know what the DECAL problems will be yet
- No detailed measurement of shower density at very small granularity
 - GEANT4 not tested at $50\mu m$ so core density may be much higher
 - GEANT4 may not give right number of low energy (~keV) photons
- We MUST do these measurements to take this concept seriously

Future measurements

- Next version of TPAC1 being made now
 - Due within one week
- Must do beam test this summer to measure hit densities in showers
 - Carefully compare against GEANT4
- TPAC1 only ~1×1cm²
 - Cannot see whole shower or measure energy resolution
- Design larger version, TPAC2, size ~2.5×3cm², and make ~20 layer DECAL in 2010
 - Find out if concept really works!
 - (Funding permitting \mathfrak{S})

			0000000