DAQ/Online for MAPS

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DAQ overview

- Like most DAQ systems, based on a state machine
 - Transitions between states driven by transfer of "records"
- Records are both dynamical agents and data storage elements
 - Record type tells each node of system which state to go to
 - Record contains data needed by node to complete transition...
 - ...and/or stores data generated by node during transition
- E.g. configurationStart record
 - Tells a node to configure some hardware
 - Contains configuration values to do this
 - Stores the configuration values read back by node as crosscheck
- Records are simple contiguous arrays in memory
 - Written to (and read from) "binary" raw data files
- All configuration data written into the records
 - No need for database for basic offline analysis

A run is set of nested levels of transitions

State

Transition

- runStart
 - configurationStart
 - bunchTrain
 - bunchTrain
 - bunchTrain
 - ...
 - configurationEnd
 - configurationStart
 - bunchTrain
 - bunchTrain
 - bunchTrain
 - ...
 - configurationEnd
 - ...
- runEnd



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Executable structure



Software overview

- Runs are labelled by runTypes
 - E.g. mpsNoise, mpsBeam, mpsLaserPositionScan, etc.
 - Each has a version number to select choices, e.g. number of x,y points in scan
- Together, runType and version determine
 - Number of configurations in run
 - Number of bunch trains in each configuration
- No databases currently used
 - There is a lack of widespread knowledge
 - Could be included as part of configuration data loading if we want
- Code requires
 - Any standard C++ compiler on standard Linux PC
 - ROOT
 - USB_DAQ driver

Existing runTypes

- mpsTest, mpsExpert, mpsNoise
 - Basic runs for setting up
- mpsConfigurationTest
 - Takes no data; just does configuration load
- mpsThreshold, mpsThresholdScan, mpsTrim, mpsTrimScan
 - Scans thresholds
- mpsBeam, mpsCosmics, mpsSource
 - For main data-taking
- mpsLaser
 - Like mpsNoise but with the laser
- mpsLaserThreshold, mpsLaserThresholdScan mpsLaserPosition, mpsLaserPositionScan
 - Scans of threshold and position with laser

To be done

• Hardware-level

- Real connection to the USB_DAQ
- Socket connection to the laser
- Online software-level
 - Precise definition of data formats
 - More realistic configuration values
 - Definition of further run types
 - GUIs for run control and monitoring
- (Semi) offline software-level
 - Conversion of raw data to ROOT trees
 - Histogramming and GUI
- Analysis software
 - Pretty much everything
 - Simulation; do digitisation process through DAQ?